

(1)

Ismeretek:

$$\mathcal{L}(1) = \frac{1}{s}$$

$$\mathcal{L}(e^{kt}) = \frac{1}{s-k} \quad \text{szó k}$$

$$\mathcal{L}(\cos(kt)) = \frac{s}{s^2+k^2} \quad \mathcal{L}(\sin(kt)) = \frac{k}{s^2+k^2}$$

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$$\mathcal{L}(t^n) = \frac{n!}{s^{n+1}}$$

$$\mathcal{L}[e^{at} f(t)] = F(s-a), \text{ ahol } F(s) = \mathcal{L}(f(t)) \Rightarrow \text{(sillapítási tétele)}$$

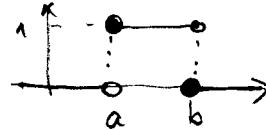
$$\mathcal{L}(e^{at} \cos kt) = \frac{s-a}{(s-a)^2+k^2} \quad \mathcal{L}(e^{at} \sin kt) = \frac{ka}{(s-a)^2+k^2}$$

$$\mathcal{L}(f') = -f(0) + s\mathcal{L}(f)$$

$$\mathcal{L}(f'') = s^2\mathcal{L}(f) - sf(0) - f'(0)$$

$$\text{Heaviside: } \begin{array}{c} f \\ \hline c \end{array} \rightarrow H_c(t) \quad \mathcal{L}(H_c) = \frac{e^{-sc}}{s} \quad s > 0$$

$$\text{Eltolási tétele: } \mathcal{L}[H_c(t) f(t-c)] = e^{-sc} \cdot \mathcal{L}(f)$$

Négyzetes

$$f(t) = H_a(t) - H_b(t)$$

$$\mathcal{L}(f) = \mathcal{L}(H_a) - \mathcal{L}(H_b) = \frac{e^{-sa} - e^{-sb}}{s}.$$

Aktuátori függvény:

$$\text{Hatalis: } u(t) \quad \text{Válasz: } v(t)$$

$$a_n u^{(n)} + \dots + a_1 u' + a_0 u = b_m v^{(m)} + \dots + b_1 v' + b_0 v \Rightarrow$$

$$a_n s^n V(s) + \dots + a_1 s V(s) + a_0 V(s) = b_m s^m U(s) + \dots + b_1 s U(s) + b_0 U(s)$$

$$Y(s) = \frac{V(s)}{U(s)} = \frac{\sum_{i=0}^m b_i s^i}{\sum_{i=0}^n a_i s^i} \quad \text{aktuátori fggv.}$$

Vizsgálájelék:

(2)

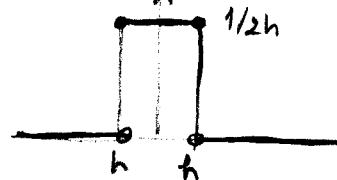
Mi a Heaviside deriváltja?

$$\mathcal{L}(H'_c(t)) = s \cdot \mathcal{L}(H_c) - H_c(0) = s \cdot \frac{e^{-sc}}{s} = e^{-sc}$$

Mi az?

Dirac delta (pillanatnyi impulusz, áramtöltés, stb.)

$$\delta_h(t) = \begin{cases} 1/2h & -h \leq t \leq h \\ 0 & \text{egébkör} \end{cases}$$



$$\text{Teljesít: } \int_{-\infty}^{\infty} \delta_h(t) dt = 1$$

$h \rightarrow 0$ határesekben is teljesül.

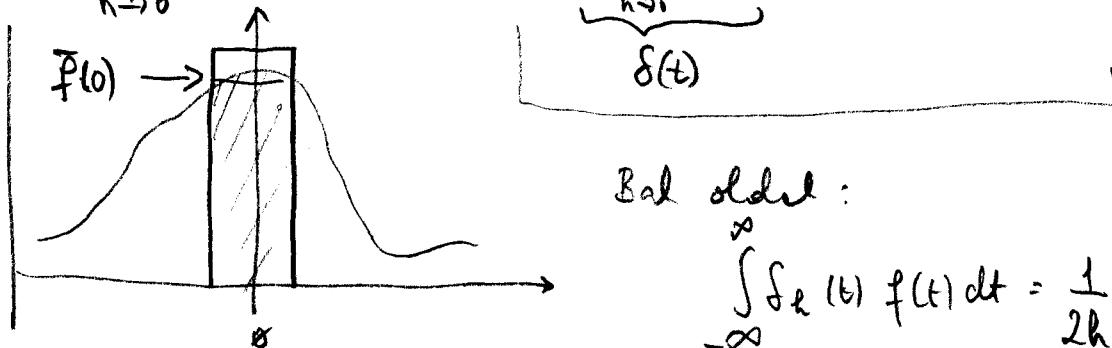
Határesekben: $\delta(t) = \lim_{h \rightarrow 0} \delta_h(t) = \begin{cases} \infty & t=0 \\ 0 & t \neq 0 \end{cases}$ ahol $\int \delta(t) dt = 1$

Haz jövőben lemeze, teljesílni, hogy

$$\lim_{h \rightarrow 0} \int \delta_h(t) dt = \int \lim_{h \rightarrow 0} \delta_h(t) dt = \int \delta(t) dt = 1$$

Megkivájtuk:

$$\lim_{h \rightarrow 0} \int \delta_h(t) f(t) dt = \int \underbrace{\lim_{h \rightarrow 0} \delta_h(t)}_{\delta(t)} f(t) dt = f(0)$$



Bal oldal:

$$\int_{-\infty}^{\infty} \delta_h(t) f(t) dt = \frac{1}{2h} \int_{-h}^{h} f(t) dt = \bar{f}(0) =$$

$$= f(\xi) \quad -h < \xi < h$$

Haz $h \rightarrow 0$, akkor $\bar{f}(0) \rightarrow f(0)$.

$\delta(t)$ kizárt a fgy. 0-beli címkéit az integrálba.

Eltolva:

$$\int_{-\infty}^{\infty} f(t) \delta(t-c) dt = f(c)$$

3

Dirac & Laplace-a

$$\mathcal{L}(f(t-c)) = \int_0^\infty e^{-st} f(t-c) dt = \int_{-\infty}^0 e^{-st} f(t-c) dt = \underline{\underline{e^{-sc}}}$$

Tehát a Heaviside deriválja a Dirac delta!

Speciális eset:

$$c=0$$

$$\mathcal{L}(f(t)) = 1$$

$$\mathcal{L}(H_0(t)) = \frac{1}{s} \quad H_0(t) = 1(t)$$

Hatás: $u = f(t)$ Válasz: súlyfázis: $v = w(t)$

$$Y(s) = \frac{V(s)}{U(s)} = \frac{W(s)}{1} \quad \text{átviteli fgg. a súlyfázis Laplace tr.}$$

Hatás: $u = 1(t)$ Válasz: átmeneti fgg.: $w = w_a(t)$

$$w_a(s) = u(s) \cdot Y(s) = \frac{1}{s} \cdot Y(s) = \underline{\underline{\frac{1}{s} W(s)}}$$

s-sel való arctás integrálásnál felül meg!

$$F(t) = \int_0^t f(\tau) d\tau \quad \text{primitív fgg.}$$

$$\mathcal{L}(F(t)) = \int_0^\infty F(t) e^{-st} dt = \left[F(t) \left(-\frac{1}{s} \right) e^{-st} \right]_0^\infty + \frac{1}{s} \int_0^\infty f(t) e^{-st} dt =$$

$\underline{\underline{u' = f \quad v = -\frac{1}{s} e^{-st} \quad F(0) = 0}}$

$$= \frac{1}{s} \mathcal{L}(f)$$

Tehát: $w_a(t) = \int_0^t w(t) dt$ átm. fgg. a súlyfázis integrálja
 ill. $w(t) = dw_a(t) / dt$

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Pelde

$$T \cdot \dot{v} + v = K \cdot u(t) \quad v(0) = 0$$

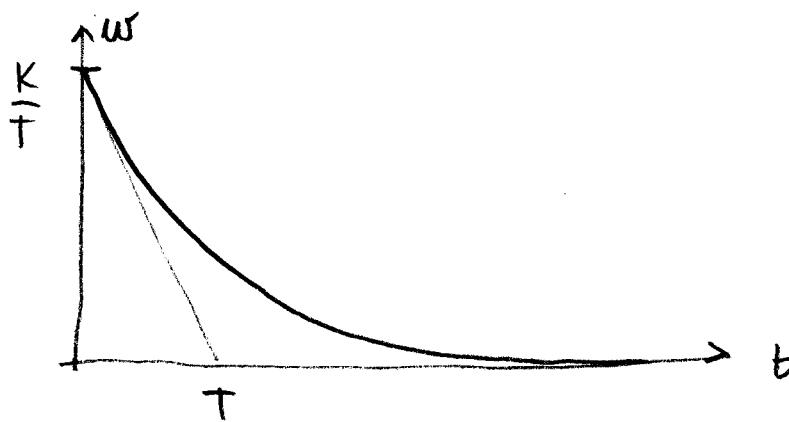
$$T(sV(s) - v(0)) + V(s) = K \cdot U(s)$$

$$\frac{V(s)}{U(s)} = \frac{V(s)}{\frac{1}{1+Ts}} = \frac{K}{1+Ts} \Rightarrow V(s) = K \cdot \frac{1}{1+Ts} \underline{V(s)}$$

(a) $u(t) = s(t) \Rightarrow U(s) = 1$

$$V(s) = K \frac{1}{1+Ts} = \frac{K}{T} \frac{1}{\frac{1}{T} + s} = W(s)$$

$$\mathcal{L}^{-1}(V) = K \mathcal{L}^{-1}\left(\frac{1}{1+Ts}\right) = \frac{K}{T} \mathcal{L}^{-1}\left(\frac{1}{\frac{1}{T} + s}\right) = \frac{K}{T} e^{-\frac{t}{T}} = \underline{v(t)} = w(t)$$



(b) $u(t) = 1(t) \Rightarrow U(s) = \frac{1}{s}$

$$V(s) = K \frac{1}{s(1+Ts)} = K \left(\frac{A}{1+Ts} + \frac{B}{s} \right)$$

$$\begin{aligned} s=1 & \frac{1}{1+T} = \frac{A}{1+T} + B \\ s=-1 & \frac{1}{-(1-T)} = \frac{A}{1-T} - B \end{aligned} \quad \left. \begin{array}{l} \\ \hline \end{array} \right\} + \quad B = \frac{1}{1+T} + \frac{1}{1-T} = \frac{\cancel{1+T} + \cancel{1-T}}{1+T} = \frac{1}{1+T} = 1$$

$$\frac{1}{1+T} + \frac{1}{1-T} = A \left(\frac{1}{T+1} - \frac{1}{T-1} \right) \quad \underline{A = -T}$$

$$\frac{T-1+T+1}{1-T^2} = A \frac{T-1-T+1}{1-T^2} = -2A$$

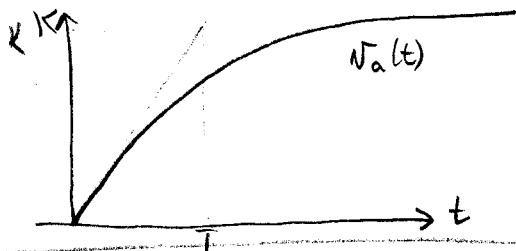
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Jedst

$$V(s) = K \left(-\frac{T}{1+Ts} + \frac{1}{s} \right) =$$

$$\mathcal{L}^{-1}(V) = -KT \underbrace{\mathcal{L}^{-1}\left(\frac{1}{1+Ts}\right)}_{\frac{1}{T} \cdot e^{-t/T}} + K \underbrace{\mathcal{L}^{-1}\left(\frac{1}{s}\right)}_1 = K \left(-e^{-t/T} + 1 \right) =$$

$$N_a(t) = K \left(1 - e^{-t/T} \right)$$



Ellenörse: $N_a(t) = K \frac{1}{T} e^{-t/T} = n(t)$

(c) $u(t) = t \cdot \lambda(t) \Rightarrow U(s) = \frac{1}{s^2}$

$$V(s) = K \frac{1}{s^2(1+Ts)} \quad \mathcal{L}^{-1}(V) = K \left(Te^{-t/T} + t - T \right)$$

$$\frac{1}{s^2(1+Ts)} = \frac{A}{s} + \frac{B}{s^2} + \frac{C}{1+Ts}$$

$$s=1 \quad \frac{1}{1+T} = A + B + \frac{C}{1+T} \quad \left. \begin{array}{l} \\ \\ \end{array} \right\} + \frac{1}{1+T} + \frac{1}{1-T} = 2B + C \left(\frac{1}{1+T} + \frac{1}{1-T} \right)$$

$$C=-1 \quad \frac{1}{1-T} = -A + B + \frac{C}{1-T}$$

$$C=2 \quad \frac{1}{4(1+2T)} = \frac{A}{2} + \frac{B}{4} + \frac{C}{1+2T} \quad \left. \begin{array}{l} \\ \\ \end{array} \right\} /2$$

$$\frac{2}{1-T^2} = \frac{2B(1-T^2)}{1-T^2} + C \frac{2}{1-T^2}$$

$$1 = 2A(1+2T) + B(1+2T) + 4C \quad \left. \begin{array}{l} \\ \\ \end{array} \right\} +$$

$$1 = B(1-T^2) + 2C$$

$$\frac{2(1+2T)}{1-T} = -2A(1+2T) + 2B(1+2T) + \frac{2C(1+2T)}{1-T}$$

ELHISZÜK

$$\textcircled{d} \quad u(t) = \sin \alpha t \quad \Rightarrow \quad U(s) = \frac{\alpha}{s^2 + \alpha^2}$$

$$V(s) = \frac{K}{T} \frac{1}{s + \frac{1}{T}} \frac{\alpha}{s^2 + \alpha^2}$$

Kélt elgyűjteni for. módszert, amit benne vanvol. a tablázatba \Rightarrow

Konvolúció

$$\text{Def: } (f * g)(t) := \int_0^t f(t-u) g(u) du \quad t > 0$$

Konvolúciós tétel:

$$\mathcal{L}(f * g) = \mathcal{L}(f) \cdot \mathcal{L}(g)$$

$$F(s) = \frac{1}{a+s} \quad G(s) = \frac{\alpha^2}{s^2 + \alpha^2}$$

$$f(t) = e^{-\alpha t} \quad g(t) = \sin \alpha t$$

$$\mathcal{L}^{-1}(F(s) \cdot G(s)) = \mathcal{L}^{-1}(\mathcal{L}(F * G)) = F * G = \int_0^t f(t-u) g(u) du =$$

$$= \int_0^t e^{-\alpha(t-u)} \sin \alpha u du = \left[+\frac{1}{\alpha} e^{-\alpha(t-u)} \sin \alpha u \right]_0^t - \frac{\alpha}{\alpha} \int_0^t e^{-\alpha(t-u)} \cos \alpha u du =$$

$$\begin{array}{c} x \\ y \\ x = +\frac{1}{\alpha} e^{-\alpha(t-u)} \\ y' = \alpha \cdot \cos(\alpha u) \end{array}$$

$$= \frac{1}{\alpha} \sin \alpha t - \frac{\alpha}{\alpha} \int_0^t e^{-\alpha(t-u)} \cos \alpha u du = \frac{1}{\alpha} \sin \alpha t - \frac{\alpha}{\alpha} \left[\left[\frac{1}{\alpha} e^{-\alpha(t-u)} \cos \alpha u \right]_0^t + \right.$$

$$\left. \frac{1}{\alpha} \cdot \cos \alpha t - \frac{1}{\alpha} e^{-\alpha t} \right]$$

$$\left. + \frac{\alpha}{\alpha} \int_0^t e^{-\alpha(t-u)} \sin \alpha u du \right]$$

I

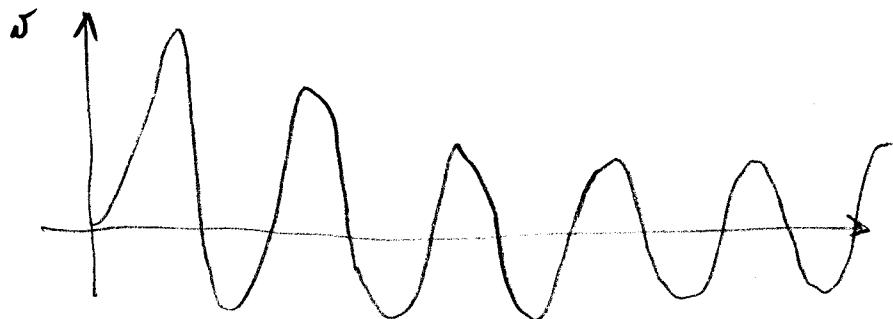
(7)

$$I = \frac{1}{a} \sin \alpha t - \frac{\alpha}{a^2} \cos \alpha t + \frac{\alpha}{a^2} e^{-at} - \frac{\alpha^2}{a^2} I$$

$$I = \frac{a}{\alpha^2 + a^2} \sin \alpha t - \frac{\alpha}{\alpha^2 + a^2} \cos \alpha t + \frac{\alpha}{\alpha^2 + a^2} e^{-at}$$

$$\alpha = \frac{1}{T} \text{ es noromi } \xrightarrow{K=1} \Rightarrow$$

$$v(t) = \frac{K}{1 + \alpha^2 T^2} \left(\sin \alpha t - \alpha T \cos \alpha t + \alpha T e^{-t/T} \right)$$



$$(e) u(t) = \delta(t - \tau) = h_\tau(t) \Rightarrow U(s) = \frac{1}{s} e^{-\tau s}$$

$$V(s) = K \frac{1}{s(1+Ts)} e^{-\tau s}$$

Ektolasi sebalik:

(b) Jeladot

$$e^{-\tau s} \cdot \mathcal{L}(v_a(t)) = \mathcal{L} \left(h_\tau(t) \cdot v_a(t - \tau) \right)$$

